

پایه ها

پایه های متغیر در زمان

سوال اول

$$|n+\rangle = \begin{pmatrix} \cos \theta/r \\ \sin \theta/r e^{i\varphi} \end{pmatrix}$$

$$|n-\rangle = \begin{pmatrix} -\sin \theta/r e^{-i\varphi} \\ \cos \theta/r \end{pmatrix}$$

الف)

$$R_n(\theta) = e^{-i\theta S_n/\hbar} = \cos \theta/r I - i \sin \theta/r \vec{\sigma} \cdot \hat{n}$$

ب)

$$\hat{n} = (\cos \varphi, \sin \varphi, 0)$$

$$\vec{\sigma} \cdot \hat{n} = \cos \varphi \sigma_x + \sin \varphi \sigma_y = \frac{(\sigma_+ + \sigma_-)}{r} \cos \varphi + \left(\frac{\sigma_+ - \sigma_-}{r i} \right) \sin \varphi$$

$$= \frac{1}{r} \left[(\cos \varphi - i \sin \varphi) \sigma_+ + (\cos \varphi + i \sin \varphi) \sigma_- \right]$$

$$= \frac{1}{r} \left[e^{-i\varphi} \sigma_+ + e^{i\varphi} \sigma_- \right]$$

$$\rightarrow R_n(\theta) = \cos \theta/r I - i \sin \theta/r \frac{1}{r} (e^{-i\varphi} \sigma_+ + e^{i\varphi} \sigma_-)$$

$$R_n(\theta) |z+\rangle = \cos \theta/r |z+\rangle - \frac{i \sin \theta/r e^{i\varphi}}{e^{-i\pi/c}} \frac{\sigma_-}{r} |z+\rangle = \begin{pmatrix} \cos \theta/r & i(\varphi - \pi/c) \\ \sin \theta/r e^{-i\varphi} & \end{pmatrix}$$

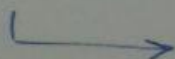
$$R_n(\theta) |z-\rangle = \cos \theta/r |z-\rangle - \frac{i \sin \theta/r e^{-i\varphi}}{e^{i\pi/c}} \frac{\sigma_+}{r} |z-\rangle = \begin{pmatrix} -\sin \theta/r e^{-i(\varphi - \pi/c)} & \\ \cos \theta/r & \end{pmatrix}$$

$$R_{n(\varphi)}(\theta) |z+\rangle = |n+(\theta, \varphi - \pi/c)\rangle$$

$$R_{n(\varphi)}(\theta) |z-\rangle = |n-(\theta, \varphi - \pi/c)\rangle$$

ج) $R_{n(\varphi)}(\theta) \leftarrow$ عمل دوران در فضای اسپینورها

$$R_n(\theta = \pi) = -I$$



عمل دوران اسپین 1/2 در دوران به سمت چپ و راست

فرض

$$a) \{A \cdot \sigma, B \cdot \sigma\} = r A \cdot B$$

$$\begin{aligned} \{A \cdot \sigma, B \cdot \sigma\} &= \{A_i \sigma_i, B_j \sigma_j\} = A_i B_j \{ \cancel{\sigma_i}, \sigma_j \} \\ &= r A_i B_i = r A \cdot B \end{aligned}$$

$$b) (\sigma \cdot A)(\sigma \cdot B) = A \cdot B + i \sigma \cdot (A \times B)$$

$$(\sigma \cdot A)(\sigma \cdot B) = (\sigma_i A_i)(\sigma_j B_j) = A_i B_j \sigma_i \sigma_j$$

$$\sigma_i \sigma_j = \begin{cases} I & i=j \\ i \epsilon_{ijk} \sigma_k & i \neq j \end{cases}$$

$$\{\sigma_i, \sigma_j\} = 2 i \epsilon_{ijk} \sigma_k$$

$$\left. \begin{aligned} \{\sigma_i, \sigma_j\} &= \delta_{ij} \rightarrow i=j : \sigma_i \sigma_j = \sigma_j \sigma_i \\ \{\sigma_i, \sigma_j\} &= \delta_{ij} \rightarrow i \neq j : \sigma_i \sigma_j = \sigma_j \sigma_i \end{aligned} \right\} \rightarrow \begin{aligned} \sigma_i \sigma_j &= i \epsilon_{ijk} \sigma_k \\ \sigma_i \sigma_j &= i \epsilon_{jik} \sigma_k \end{aligned}$$

$$\longrightarrow \sigma_i \sigma_j = \delta_{ij} + i \epsilon_{ijk} \sigma_k$$

$$\longrightarrow (\sigma \cdot A)(\sigma \cdot B) = A_i B_j (\delta_{ij} + i \epsilon_{ijk} \sigma_k)$$

$$= A_i B_j \delta_{ij} + i \epsilon_{ijk} A_i B_j \sigma_k$$

$$= A \cdot B + i (A \times B)_k \sigma_k = A \cdot B + i (A \times B) \cdot \sigma$$

Q(2):

$$\begin{aligned} c) e^{i\alpha\sigma_x} \sigma_z e^{-i\alpha\sigma_x} &= (\cos\alpha + i\sigma_x \sin\alpha) \sigma_z (\cos\alpha - i\sigma_x \sin\alpha) \\ &= \sigma_z \cos^2\alpha + \sigma_x \sigma_z \sigma_x \sin^2\alpha + i[\sigma_x, \sigma_z] \sin\alpha \end{aligned}$$

المعطى: $\sigma_x \sigma_z = -\sigma_z \sigma_x$, $\sigma_x^2 = I$. $[\sigma_x, \sigma_z] = -2i\sigma_y$

$$\begin{aligned} \Rightarrow e^{i\alpha\sigma_x} \sigma_z e^{-i\alpha\sigma_x} &= \sigma_z \cos^2\alpha - \sigma_z \sigma_x^2 \sin^2\alpha + 2\sigma_y \sin\alpha \cos\alpha \\ &= \sigma_z (\cos^2\alpha - \sin^2\alpha) + \sigma_y (2\sin\alpha \cos\alpha) \end{aligned}$$

$$\Rightarrow e^{i\alpha\sigma_x} \sigma_z e^{-i\alpha\sigma_x} = \sigma_z \cos(2\alpha) + \sigma_y \sin(2\alpha)$$

سوال سوم

$$H = \frac{\alpha}{\hbar^2} (S_1^2 + S_2^2) + \frac{\alpha}{\hbar} S_z = \frac{\alpha}{\hbar^2} (S^2 - S_z^2) + \frac{\alpha}{\hbar} S_z$$

$$= \frac{\alpha}{\hbar^2} S^2 - \frac{\alpha}{\hbar^2} (S_z^2 - \hbar S_z), \quad H|\psi\rangle = E|\psi\rangle$$

$$|\psi\rangle = \sum_{S,m} A_{S,m} |S,m\rangle \rightarrow \sum_{S,m} A_{S,m} \left(\frac{\alpha}{\hbar^2} S(S+1)\hbar^2 - \frac{\alpha}{\hbar^2} (m^2\hbar^2 - m\hbar^2) \right) |S,m\rangle$$

$$= \sum_{S,m} A_{S,m} (S(S+1) - m(m-1)) \alpha |S,m\rangle = \sum_{S,m} E A_{S,m} |S,m\rangle$$

$$\rightarrow A_{S,m} (E - \alpha(S(S+1) - m(m-1))) = 0$$

$$\rightarrow E = \alpha[S(S+1) - m(m-1)], \quad |E_{S,m}\rangle = |S,m\rangle$$

$$S = 5/2 \rightarrow E_m = \alpha \left(\frac{35}{4} - m(m-1) \right)$$

$$m = 5/2 \rightarrow E_{5/2} = \alpha \left(\frac{35}{4} - \frac{15}{4} \right) = 5\alpha$$

$$m = 3/2 \rightarrow E_{3/2} = \alpha \left(\frac{35}{4} - \frac{3}{4} \right) = 8\alpha$$

$$m = 1/2 \rightarrow E_{1/2} = \alpha \left(\frac{35}{4} + \frac{1}{4} \right) = 9\alpha$$

$$m = -1/2 \rightarrow E_{-1/2} = \alpha \left(\frac{35}{4} - \frac{3}{4} \right) = 8\alpha$$

$$m = -3/2 \rightarrow E_{-3/2} = \alpha \left(\frac{35}{4} - \frac{15}{4} \right) = 5\alpha$$

$$m = -5/2 \rightarrow E_{-5/2} = \alpha \left(\frac{35}{4} - \frac{35}{4} \right) = 0$$

$$E = 5\alpha \quad \text{تکانه: } |5/2, 5/2\rangle, |5/2, -3/2\rangle$$

$$E = 8\alpha \quad \text{تکانه: } |5/2, 3/2\rangle, |5/2, -1/2\rangle$$

بقیه حالات انرژی تکانه ندارند.

Q.43:

$$\Psi = Kr (\cos\phi \sin\theta + \sin\phi \sin\theta + 2\cos\theta) e^{-\alpha r}$$

Angular Part:

$$\Psi(\theta, \phi) = k' (\cos\phi \sin\theta + \sin\phi \sin\theta + 2\cos\theta)$$

$$\Rightarrow k'^2 \int_0^\pi d\theta \int_0^{2\pi} (\cos\phi \sin\theta + \sin\phi \sin\theta + 2\cos\theta)^2 \sin\theta d\phi = 1 \quad \Rightarrow$$

$$\text{Using: } \cos\phi = \frac{1}{2}(e^{i\phi} + e^{-i\phi})$$

$$\sin\phi = \frac{1}{2i}(e^{i\phi} - e^{-i\phi})$$

$$\Psi(\theta, \phi) = k' \left[\frac{1}{2}(e^{i\phi} + e^{-i\phi}) \sin\theta + \frac{1}{2i}(e^{i\phi} - e^{-i\phi}) \sin\theta + 2\cos\theta \right]$$

$$= k' \left[-\frac{1}{2}(1-i)\sqrt{\frac{8\pi}{3}} Y_1^1 + \frac{1}{2}(1+i)\sqrt{\frac{8\pi}{3}} Y_1^{-1} + 2\sqrt{\frac{4\pi}{3}} Y_1^0 \right]$$

$$\Rightarrow k'^2 \left[\frac{1}{2} \frac{8\pi}{3} + \frac{1}{2} \frac{8\pi}{3} + 4 \cdot \frac{4\pi}{3} \right] = 1 \Rightarrow k' = \sqrt{\frac{1}{8\pi}}$$

$$\Rightarrow \boxed{\Psi(\theta, \phi) = \sqrt{\frac{1}{8\pi}} \left[-\frac{1}{2}(1-i)\sqrt{\frac{8\pi}{3}} Y_1^1 + \frac{1}{2}(1+i)\sqrt{\frac{8\pi}{3}} Y_1^{-1} + 2\sqrt{\frac{4\pi}{3}} Y_1^0 \right]}$$

Ans) $\sqrt{\langle L^2 \rangle} = \sqrt{2(2+1)} \hbar = \sqrt{2} \hbar$

$$\begin{aligned} \rightarrow) \langle \Psi | L_z | \Psi \rangle &= r'^2 \left[\frac{1}{2} \frac{8\pi}{3} \hbar (Y_1^1)^2 + \frac{1}{2} \frac{8\pi}{3} (-\hbar) (Y_1^{-1})^2 + 4 \frac{4\pi}{3} (0) Y_1^0 \right] \\ &= \frac{1}{8\pi} \left[\frac{1}{2} \frac{8\pi}{3} \hbar - \frac{1}{2} \frac{8\pi}{3} \hbar \right] = 0 \end{aligned}$$

$$\begin{aligned} \rightarrow) P &= |\langle L_z = +\hbar | \Psi(\theta, \phi) \rangle|^2 \\ &= \frac{1}{8\pi} \times \frac{1}{2} \times \frac{8\pi}{3} = \frac{1}{6} \end{aligned}$$

سؤال ٥

$$\hat{H} = \begin{cases} -\vec{\mu} \cdot \vec{B} & \vec{B} = B \hat{z} & 0 < t < T \\ -\vec{\mu} \cdot \vec{B} & \vec{B} = B \hat{y} & T < t < 2T \end{cases}$$

$$\vec{\mu} = \mu_B \vec{\sigma}$$

$$\hat{H} = -\mu_B B \begin{cases} \sigma_z & 0 < t < T \\ \sigma_y & T < t < 2T \end{cases}$$

$$|\psi(0)\rangle = |\alpha+\rangle = \frac{|\alpha+\rangle + |\alpha-\rangle}{\sqrt{2}}$$

$$0 < t < T \quad \hat{H} = -\mu_B B \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$$

$$|\psi(t)\rangle = e^{-i\hat{H}t/\hbar} |\psi(0)\rangle = e^{+i\mu_B B t/\hbar \sigma_z} |\psi(0)\rangle$$

$$= \left(\cos\left(\frac{\mu_B B t}{\hbar}\right) I + i \sin\left(\frac{\mu_B B t}{\hbar}\right) \sigma_z \right) \frac{|\psi(0)\rangle}{|\alpha+\rangle}$$

$$= \cos\left(\frac{\mu_B B t}{\hbar}\right) |\alpha+\rangle + i \sin\left(\frac{\mu_B B t}{\hbar}\right) |\alpha-\rangle$$

$$t = T \longrightarrow |\psi(T)\rangle = \cos\left(\frac{\mu_B B T}{\hbar}\right) |\alpha+\rangle + i \sin\left(\frac{\mu_B B T}{\hbar}\right) |\alpha-\rangle$$

$$T < t < 2T \quad |\psi(t)\rangle = e^{-i\hat{H}(t-T)/\hbar} |\psi(T)\rangle = e^{+i\mu_B B(t-T)/\hbar \sigma_y} |\psi(T)\rangle$$

$$= \left(\cos\left(\frac{\mu_B B(t-T)}{\hbar}\right) I + i \sin\left(\frac{\mu_B B(t-T)}{\hbar}\right) \sigma_y \right) |\psi(T)\rangle$$

$$= \cos\left(\frac{\mu_B B(t-T)}{\hbar}\right) |\psi(T)\rangle + i \sin\left(\frac{\mu_B B(t-T)}{\hbar}\right) \sigma_y |\psi(T)\rangle$$

$$\sigma_y = \begin{pmatrix} & -i \\ i & \end{pmatrix}$$

$$\sigma_y |\alpha+\rangle = \begin{pmatrix} & -i \\ i & \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -i \\ i \end{pmatrix} = -i |\alpha-\rangle$$

$$\sigma_y |\alpha-\rangle = \begin{pmatrix} & -i \\ i & \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} i \\ i \end{pmatrix} = i |\alpha+\rangle$$

$$|\psi(r, T)\rangle = \cos\left(\frac{\mu_B T}{\hbar}\right) |\psi(r, T)\rangle + i \sin\left(\frac{\mu_B T}{\hbar}\right) \left\{ \cos\left(\frac{\mu_B T}{\hbar}\right) \underbrace{\sigma_y |\alpha_+\rangle}_{-i |\alpha_-\rangle} + i \sin\left(\frac{\mu_B T}{\hbar}\right) \underbrace{\sigma_y |\alpha_-\rangle}_{i |\alpha_+\rangle} \right\}$$

$$= \left\{ \cos^r\left(\frac{\mu_B T}{\hbar}\right) - i \sin^r\left(\frac{\mu_B T}{\hbar}\right) \right\} |\alpha_+\rangle + \left\{ i \sin\left(\frac{\mu_B T}{\hbar}\right) \cos\left(\frac{\mu_B T}{\hbar}\right) + \sin\left(\frac{\mu_B T}{\hbar}\right) \cos\left(\frac{\mu_B T}{\hbar}\right) \right\} |\alpha_-\rangle$$

$$P\left(\frac{1}{2}|\alpha_+\rangle \text{ } \overbrace{\text{}}^{\text{}} \right) = |\langle \alpha_+ | \psi(r, T) \rangle|^r$$

$$= \left| \frac{\cos^r\left(\frac{\mu_B T}{\hbar}\right) - i \sin^r\left(\frac{\mu_B T}{\hbar}\right)}{\frac{1 + \cos\left(\frac{r\mu_B T}{\hbar}\right)}{r}} \frac{1 - \cos\left(\frac{r\mu_B T}{\hbar}\right)}{r} \right|^r$$

$$= \frac{1}{r} \left\{ \left(1 + \cos\left(\frac{r\mu_B T}{\hbar}\right)\right)^r + \left(1 - \cos\left(\frac{r\mu_B T}{\hbar}\right)\right)^r \right\}$$

$$= \frac{1}{r} \left\{ r + r \cos^r\left(\frac{r\mu_B T}{\hbar}\right) \right\} = \frac{1}{r} \left\{ 1 + \cos^r\left(\frac{r\mu_B T}{\hbar}\right) \right\}$$

سوال ششم:

$$[J_x J_y, J_z] + [J_x, J_y J_z] = J_x \overbrace{[J_y, J_z]}^{i\hbar J_x} + \overbrace{[J_x, J_z]}^{-i\hbar J_y} J_y + \overbrace{[J_x, J_y]}^{i\hbar J_z} J_z + J_y \overbrace{[J_x, J_z]}^{-i\hbar J_y}$$

$$= i\hbar J_x^2 - i\hbar J_y^2 + i\hbar J_z^2 - i\hbar J_y^2 = i\hbar (J_x^2 - 2J_y^2 + J_z^2)$$

سؤال هفتم

$$\begin{cases} |1,1\rangle = |++\rangle \\ |1,0\rangle = \frac{1}{\sqrt{2}}(|+-\rangle + |-+\rangle) \\ |1,-1\rangle = |--\rangle \end{cases}$$

الف) $|0,0\rangle = \frac{1}{\sqrt{2}}(|+-\rangle - |-+\rangle)$

ب)
$$\begin{aligned} |\psi\rangle &= \frac{1}{\sqrt{2}} \times \frac{1}{\sqrt{2}} (|1,0\rangle + |0,0\rangle) + \frac{1}{\sqrt{2}} |1,-1\rangle \\ &= \frac{1}{2} |1,0\rangle + \frac{1}{2} |0,0\rangle + \frac{1}{\sqrt{2}} |1,-1\rangle \end{aligned}$$

آماران انتظاری مکانی کل S^2 و S_z در حالت $|\psi\rangle$ را محاسبه کنید.

1. $P(l=0) = |\langle 0,0 | \psi \rangle|^2 = \frac{1}{2}$

پس است از آماران انتظاری مکانی کل S^2 و S_z در حالت $|\psi\rangle$ را محاسبه کنید. l و m در این محاسبات به کار می آید.

$$P(l=1) = P(l=1, m=1) + P(l=1, m=0) + P(l=1, m=-1)$$

$$P(l=1, m=0) = |\langle 1,0 | \psi \rangle|^2 = \frac{1}{4}$$

$$P(l=1, m=1) = |\langle 1,1 | \psi \rangle|^2 = 0$$

$$P(l=1, m=-1) = |\langle 1,-1 | \psi \rangle|^2 = \frac{1}{4}$$

$$P(l=1) = 0 + \frac{1}{4} + \frac{1}{4} = \frac{1}{2}$$

سوال ۵

$$P = \begin{pmatrix} \langle ++ | P | ++ \rangle & \langle ++ | P | + - \rangle & \langle ++ | P | - + \rangle & \langle ++ | P | -- \rangle \\ \langle + - | P | ++ \rangle & \langle + - | P | + - \rangle & \langle + - | P | - + \rangle & \langle + - | P | -- \rangle \\ \langle - + | P | ++ \rangle & \langle - + | P | + - \rangle & \langle - + | P | - + \rangle & \langle - + | P | -- \rangle \\ \langle -- | P | ++ \rangle & \langle -- | P | + - \rangle & \langle -- | P | - + \rangle & \langle -- | P | -- \rangle \end{pmatrix}$$

در واقع، رابطه‌ی بالا با فرض زیر درست می‌آید.

$$|++\rangle \equiv \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad |+-\rangle \equiv \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \quad |-+\rangle \equiv \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \quad |--\rangle \equiv \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$|\alpha\rangle = \alpha_1 |+\rangle + \alpha_2 |-\rangle = \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix}$$

$$|\beta\rangle = \beta_1 |+\rangle + \beta_2 |-\rangle = \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix}$$

$$|\alpha\rangle \otimes |\beta\rangle = \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} \otimes \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} = \begin{pmatrix} \alpha_1 \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} \\ \alpha_2 \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} \alpha_1 \beta_1 \\ \alpha_1 \beta_2 \\ \alpha_2 \beta_1 \\ \alpha_2 \beta_2 \end{pmatrix}$$

$$|\beta\rangle \otimes |\alpha\rangle = \begin{pmatrix} \beta_1 \\ \beta_2 \end{pmatrix} \otimes \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = \begin{pmatrix} \alpha_1 \beta_1 \\ \alpha_2 \beta_1 \\ \alpha_1 \beta_2 \\ \alpha_2 \beta_2 \end{pmatrix}$$

$$P|\alpha\rangle \otimes |\beta\rangle = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \alpha_1 \beta_1 \\ \alpha_1 \beta_2 \\ \alpha_2 \beta_1 \\ \alpha_2 \beta_2 \end{pmatrix} = \begin{pmatrix} \alpha_1 \beta_1 \\ \alpha_2 \beta_1 \\ \alpha_1 \beta_2 \\ \alpha_2 \beta_2 \end{pmatrix} = |\beta\rangle \otimes |\alpha\rangle$$

ادامی سوال مشق 2

$$\sigma_0 \otimes \sigma_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & 0 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ 0 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & 1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad (C)$$

$$\sigma_1 \otimes \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \otimes \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$\sigma_2 \otimes \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \otimes \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix}$$

$$\sigma_3 \otimes \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\sigma_0 \otimes \sigma_0 + \sigma_1 \otimes \sigma_1 + \sigma_2 \otimes \sigma_2 + \sigma_3 \otimes \sigma_3 = 2 \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = 2P$$